

Lecture 14

Note Title

9/24/2007

Topics

- order of difference equation
- convolution vs. difference equation
- example on computing impulse response from DE
- CT convolution
- CT - Differential Equation

Examples of Recursive DE

Accumulator : $y[n] = y[n-1] + u[n]$

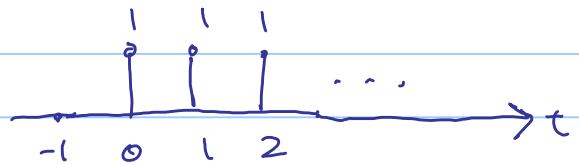
How do we generate impulse response $h[n]$ given DE?

Set ① $u[n] = \delta[n]$

② Initial state is zero — $h[n]$ is the zero-state output

$$\Rightarrow y[-1] = 0$$

n	$u[n]$	$y[n] = y[n-1] + u[n]$
-1	0	0
0	1	1
1	0	1
2	0	1
3	0	1
⋮	⋮	⋮



Ex 2 $y[n] = \underbrace{u[n] + u[n-1]}_{\text{Input}} + \underbrace{3y[n-1] + 4y[n-2]}_{\text{Two prior output}}$

$$y[n] - 3y[n-1] - 4y[n-2] = u[n] + u[n-1]$$

↑ Register
↑ Register
↑ Register
"Direct" Form I

Is the order = 3 ? No

$$\text{Order} = \max \left[\begin{array}{l} \text{memory registers required on the output} \\ \text{memory} \quad \vee \quad \vee \quad \vee \quad \vee \quad \vee \quad \text{input} \end{array} \right]$$

= 2

The trick is to introduce an intermediate signal $v[n]$

$$\begin{cases} v[n] - 3v[n-1] - 4v[n-2] = u[n] \\ y[n] = v[n] + v[n-1] \end{cases} \quad \begin{array}{l} \text{"Direct"} \\ \text{Form} \\ \text{II} \end{array}$$

⇒ Need 2 registers only : $v[n-1]$ and $v[n-2]$

Rf: $y[n] = v[n] + v[n-1]$

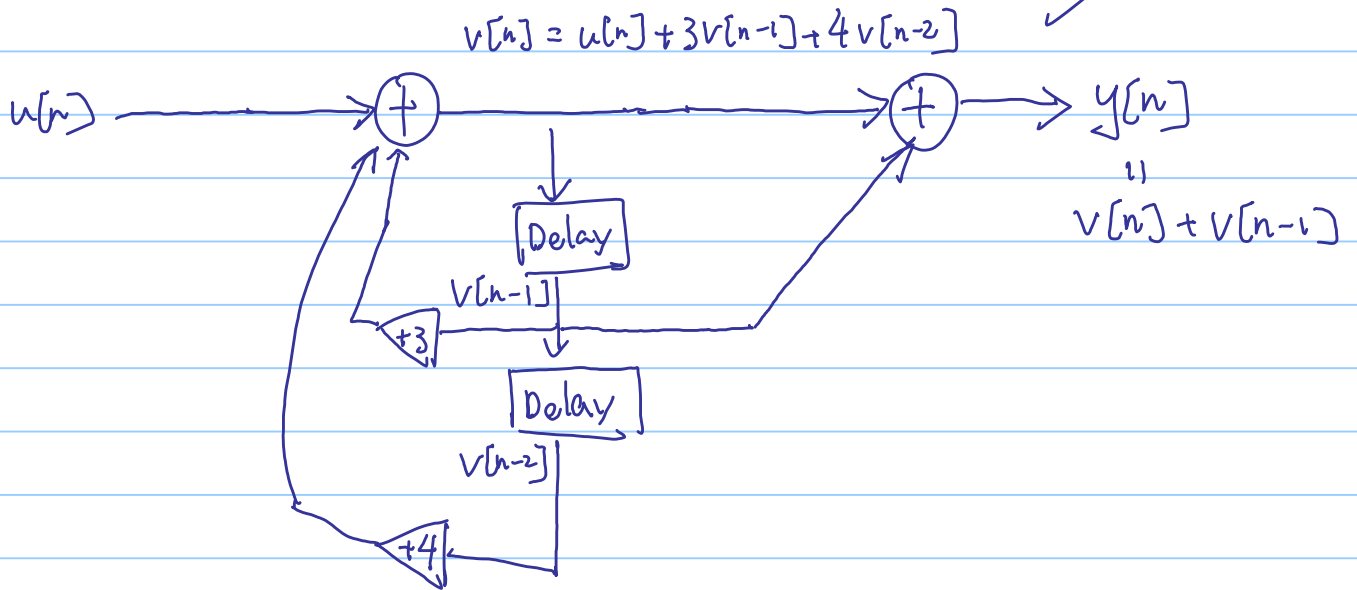
-3 $y[n-1] = -3v[n-1] - 3v[n-2]$

+ $-4y[n-2] = -4v[n-2] - 4v[n-3]$

$$y[n] - 3y[n-1] - 4y[n-2] = v[n] - 2v[n-1] - 7v[n-2] - 4v[n-3]$$

$$= \underbrace{(v[n] - 3v[n-1] - 4v[n-2])}_{\rightarrow u[n]} + \underbrace{(v[n-1] - 3v[n-2] - 4v[n-3])}_{\rightarrow u[n-1]}$$

$$\Rightarrow y[n] - 3y[n-1] - 4y[n-2] = u[n] + u[n-1]$$

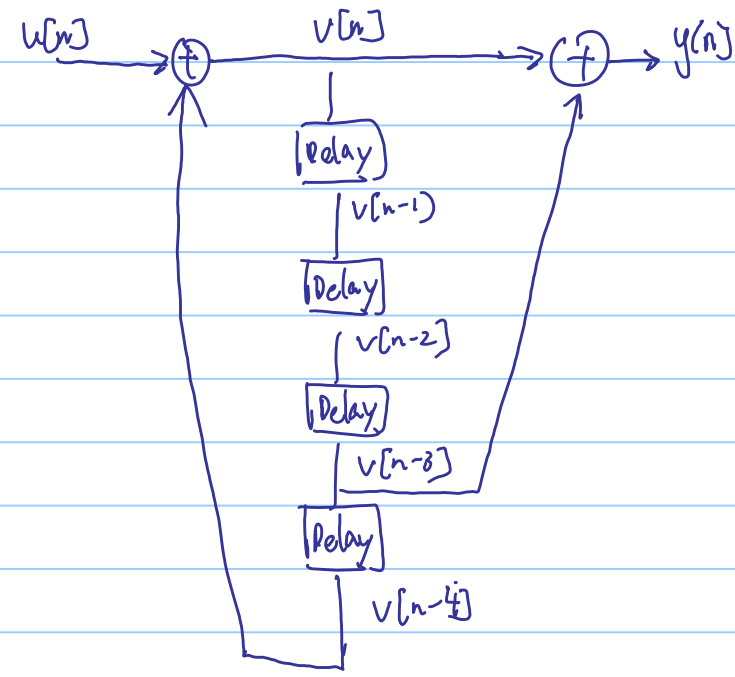


ex/ $y[n] - y[n-4] = u[n] + u[n-3]$

Convince Yourself

One	0
Two	5
Three	1
Four	2
> 4	0

$$\begin{cases} v[n] - v[n-4] = u[n] \\ y[n] = v[n] + v[n-3] \end{cases}$$



Two ways to compute the output of a DT LTI system:

Convolution

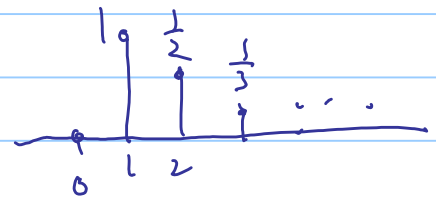
DE

$$y[n] = \sum_{k=-\infty}^{\infty} u[k] h[n-k]$$

$$y[n] - y[n-1] = u[n] + u[n-3]$$

- | | | |
|--------------------------|---------------------------|----------------------------------|
| ① Implementation | BAD for IIR | GOOD |
| ② Non-zero Initial State | Cannot handle | $y[-1] = 3/4$ ex |
| ③ Generality | Works for all LTI systems | Only works for Lumped LTI system |

Ex/ $h[k] = \frac{1}{k} \quad k > 0$



$$y[n] = \sum_{k=-\infty}^{\infty} u[k] h[n-k]$$

$$= \sum_{k=-\infty}^{\infty} u[k] \frac{1}{n-k}$$

Assume my input $u[k]$ starts at $k=0$

$$= \sum_{k=0}^{n-1} u[k] \frac{1}{n-k}$$

$$y[n+1] = \sum_{k=0}^n u[k] \frac{1}{(n+1)-k} = u[n+1] + \underbrace{\sum_{k=0}^{n-1} u[k] \frac{1}{(n+1)-k}}$$

— Not a lumped sys!!

cannot be expressed using $y[n], y[n-1], y[n-2], \dots$