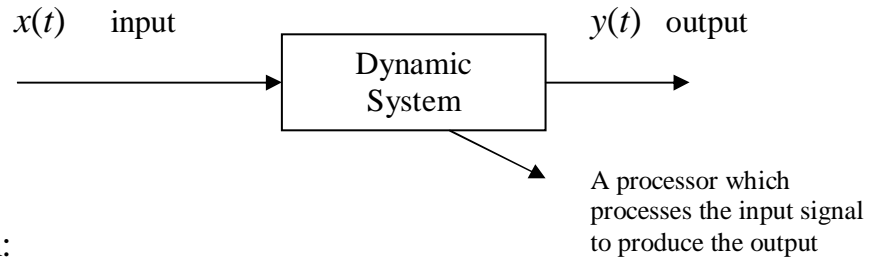


## Chapter 5 The Laplace Transform

### 5-1 Introduction

#### (1) System analysis

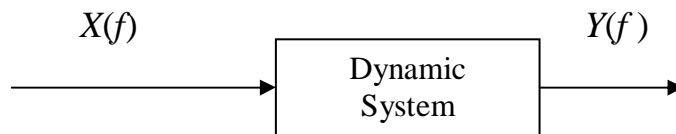


Linear Dynamic system:

$$\frac{dy^{(n)}(t)}{dt^n} + a_1 \frac{dy^{(n-1)}(t)}{dt^{n-1}} + \dots + a_n y(t) = b_0 \frac{dx^{(m)}(t)}{dt^m} + \dots + b_m x(t)$$

Question: Can we determine  $y(t)$  for a given  $x(t)$ ?

Answer: Use Fourier transform to convert the ODE into algebraic equation!



$$H(f)$$

$$Y(f) = H(f)X(f)$$

$$y(t) = F^{-1}(Y(f))$$

#### (2) Two Problems

1. Some common signals do not have a Fourier Transform !

Example: What is the Fourier transform of  $x(t) = e^t u(t)$  ?

$$X(f) = \int_{-\infty}^{\infty} e^t u(t) e^{-j2\pi ft} dt = \int_0^{\infty} e^t e^{-j2\pi ft} dt \text{ does not exist for any } f \text{ as } e^t$$

blows up when  $t \rightarrow \infty$ .

Even though  $x(t)$  grows unbounded as  $t \rightarrow \infty$ , it may still exist as an intermediate step in a larger system. Consider the output when  $x(t)$  is fed into a system with impulse response  $h(t) = (3e^{-2t} - 2e^{-t})u(t)$ .

$$\begin{aligned}
 y(t) &= \int_{-\infty}^{\infty} e^{t-\tau} u(t-\tau) (3e^{-2\tau} - 2e^{-\tau}) \mu(\tau) d\tau \\
 &= \int_0^t e^{t-\tau} (3e^{-2\tau} - 2e^{-\tau}) d\tau \\
 &= (e^{-t} - e^{-2t}) u(t)
 \end{aligned}$$

which certainly decays to 0 as  $t \rightarrow \infty$ .

## 2. Initial Condition Problem

Say we know the output  $y(t)$  of the above dynamic system is 5 at  $t=0$ .

Nowhere in the Fourier system equations below we could insert this information:

$$\begin{aligned}
 Y(f) &= H(f)X(f) \\
 y(t) &= F^{-1}(Y(f))
 \end{aligned}$$

## (3) Solution: Laplace Transform

Even though  $x(t)$  does not go to zero (when  $t \rightarrow \infty$ ), but  $x(t)e^{-\sigma t}$  may for large enough  $\alpha$ .

⇒ We will assume all signals are “causal” :  $x(t) = 0$  for  $t < 0$

⇒ Fourier transform of  $x(t)e^{-\sigma t}$  :

$$\begin{aligned}
 \int_0^{\infty} (x(t)e^{-\sigma t}) e^{-j\omega t} dt &= \int_0^{\infty} x(t) e^{-(\sigma + j\omega)t} dt \\
 &= \int_0^{\infty} x(t) e^{-st} dt \quad \text{where } s = \sigma + j\omega \\
 &= \text{Laplace Transform of } x(t)
 \end{aligned}$$

- We will see how Laplace transform takes care of initial conditions later.
- Even though inverse Laplace Transform exists, it involves more sophisticated concepts from complex number theory. Just like Inverse Fourier Transform, we will just use table (and Matlab).
- Laplace transform is just as nice as Fourier Transform:

$$Y(s) = H(s)X(s) + \text{initial conditions}$$

$$y(t) = L^{-1}(Y(s))$$

- Fourier Transform of  $x(t)u(t)$  can be obtained by substituting  $s = j\omega$  (i.e. setting  $\sigma = 0$ ) in  $X(s)$ .<sup>1</sup>

<sup>1</sup> If the Region of Convergence of  $X(s)$  does not include the imaginary axis ( $s = j\omega$ ), then its Fourier Transform does not exist. (More later)

## 5-2 Examples of Evaluating Laplace Transforms using the definition

### (1) Step function $x(t)=u(t)$

$$\begin{aligned}
 L[u(t)] &= \int_0^{\infty} e^{-st} dt \\
 &= -\frac{1}{s} \int_0^{\infty} e^{-st} d(-st) \\
 &= \left[ -\frac{e^{-st}}{s} \right]_{t=0}^{t=\infty} \\
 &= -\frac{1}{s} \lim_{t \rightarrow \infty} (e^{-st}) + \frac{1}{s} \\
 &= -\frac{1}{s} \lim_{t \rightarrow \infty} (e^{-\operatorname{Re}(s)t} e^{-j \operatorname{Im}(s)t}) + \frac{1}{s} \\
 &= \begin{cases} 1/s & \text{if } \operatorname{Re}(s) > 0 \text{ as } e^{-\operatorname{Re}(s)t} \xrightarrow{t \rightarrow \infty} 0 \\ \infty & \text{if } \operatorname{Re}(s) < 0 \text{ as } e^{-\operatorname{Re}(s)t} \xrightarrow{t \rightarrow \infty} \infty \\ \text{not sure} & \text{if } \operatorname{Re}(s) = 0 \text{ as } \lim_{t \rightarrow \infty} e^{-j \operatorname{Im}(s)t} = ? \end{cases}
 \end{aligned}$$

When  $\operatorname{Re}(s) = 0$ , define  $\omega = \operatorname{Im}(s)$ . The integral becomes  $\int_0^{\infty} e^{-j\omega t} dt = \int_{-\infty}^{\infty} u(t) e^{-j\omega t} dt$  which is the Fourier transform of  $u(t)$ . From chapter 4, we know that

$$F[u(t)] = \frac{1}{j\omega} + 2\pi\delta(\omega)$$

Note that for  $\omega \neq 0$ , the Fourier Transform can be evaluated by substituting  $s=j\omega$  in the expression  $1/s$ .

### (2) Exponential $x(t) = e^{-\alpha t} u(t)$

$$\begin{aligned}
 L[e^{-\alpha t} u(t)] &= \int_0^{\infty} e^{-\alpha t} e^{-st} dt \\
 &= \int_0^{\infty} e^{-(s+\alpha)t} dt \\
 &= \frac{-1}{s+\alpha} \int_0^{\infty} e^{-(s+\alpha)t} d-(s+\alpha)t \\
 &= \frac{-1}{s+\alpha} \lim_{t \rightarrow \infty} e^{-(s+\alpha)t} + \frac{1}{s+\alpha} \\
 &= -\frac{1}{s+\alpha} \lim_{t \rightarrow \infty} (e^{-\operatorname{Re}(s+\alpha)t} e^{-j \operatorname{Im}(s+\alpha)t}) + \frac{1}{s+\alpha} \\
 &= \begin{cases} 1/(s+\alpha) & \text{if } \operatorname{Re}(s) > -\operatorname{Re}(\alpha) \text{ as } e^{-\operatorname{Re}(s+\alpha)t} \xrightarrow{t \rightarrow \infty} 0 \\ \infty & \text{if } \operatorname{Re}(s) < -\operatorname{Re}(\alpha) \text{ as } e^{-\operatorname{Re}(s+\alpha)t} \xrightarrow{t \rightarrow \infty} \infty \\ 1/(s+\alpha) + 2\pi\delta(\operatorname{Im}(s)) & \text{if } \operatorname{Re}(s) = -\operatorname{Re}(\alpha) \text{ as } \lim_{t \rightarrow \infty} e^{-j \operatorname{Im}(s+\alpha)t} = ? \end{cases}
 \end{aligned}$$

- (3)  $x(t) = \delta(t)$  Recall that the impulse function is represented as a limit of convention functions straddling the origin. To incorporate the “full” delta function, we define the lower limit of our Laplace integral to be  $0^-$ .

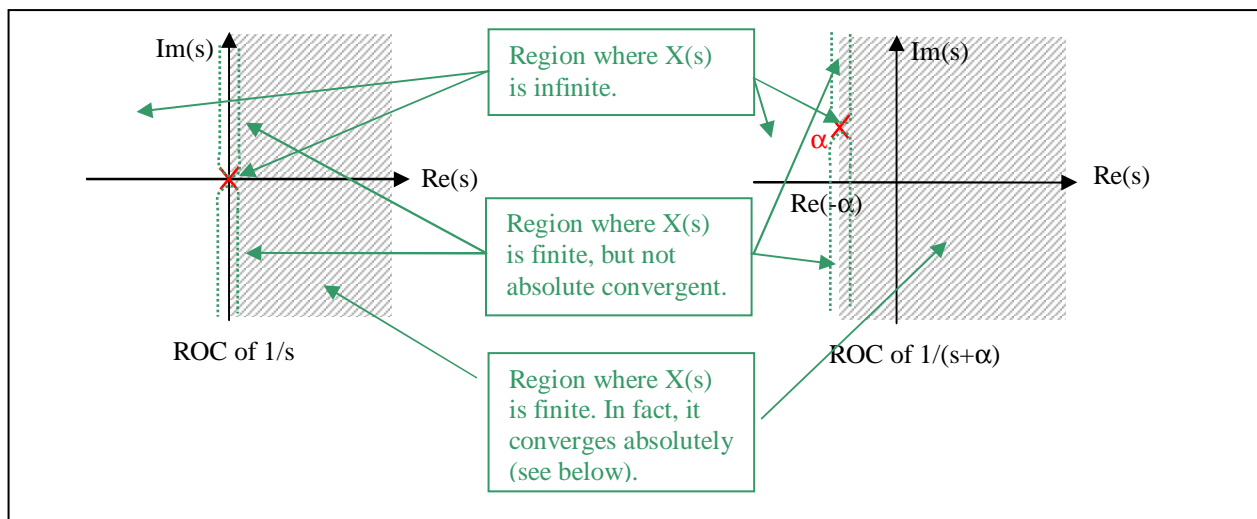
$$\begin{aligned} L[\delta(t)] &= \int_0^{\infty} \delta(t) e^{-st} dt \\ &= e^{-st} \Big|_{t=0^-} = e^{-\sigma} e^{-j\omega t} \Big|_{t=0^-} \\ &= e^{-\sigma} (\cos \omega t - j \sin \omega t) \Big|_{t=0^-} \\ &= 1 \end{aligned}$$

No constraint on  $s$ .

### 5-2B Region of Convergence (ROC)

ROC: Pictorial description of the value  $s$  where the Laplace Transform of a function exists.

#### Anatomy of ROC



#### Properties of ROC

1. It is bordered by the RIGHTMOST POLES of  $X(s)$ . A pole is defined by the complex value  $s'$  such that the algebraic  $X(s')$  is infinite.
2. If  $s'$  is in the interior of the ROC, then all  $s$  with  $\text{Re}(s) = \text{Re}(s')$  are inside the ROC.
3. It extends to positive infinity

In the interior of ROC (not boundary), not only does the Laplace integral converge, it converges ABSOLUTELY.

Normal convergent (or  $X(s)$  is finite):  $X(s) = \int_0^{\infty} x(t)e^{-st} dt < \infty$

Absolute convergent:  $\int_0^{\infty} |x(t)e^{-st}| dt < \infty$

We cannot prove that without venturing into a branch of mathematics called the complex variable theory.

However, knowing that  $X(s)$  converges absolutely inside the ROC, we can explain some of the properties:

For example:

2. If  $s'$  is in the interior of the ROC, then all  $s$  with  $\text{Re}(s) = \text{Re}(s')$  are inside the ROC.

$$\int_0^{\infty} |x(t)e^{-st}| dt = \int_0^{\infty} |x(t) \exp(-\text{Re}(st) - j \text{Im}(st))| dt$$

Why?

$$= \int_0^{\infty} |x(t) \exp(-\text{Re}(st))| \cdot |\exp(-j \text{Im}(st))| dt$$

Note that  $|\exp(-j \text{Im}(st))| = \sqrt{\cos^2(\text{Im}(st)) + \sin^2(\text{Im}(st))} = 1$ , we have

$$\int_0^{\infty} |x(t)e^{-st}| dt = \int_0^{\infty} |x(t) \exp(-\text{Re}(st))| dt \text{ which does not depend on } \text{Im}(s).$$

3. ROC extends to positive infinity.

Assume  $p$  is in the ROC. Let  $q$  be a complex number with  $\text{Re}(q) > \text{Re}(p)$ .

$$\int_0^{\infty} |x(t)e^{-qt}| dt = \int_0^{\infty} |x(t)| \exp(-\text{Re}(qt)) dt \leq \int_0^{\infty} |x(t)| \exp(-\text{Re}(pt)) dt < \infty.$$

The second last inequality is due to the fact that  $|\exp(-\text{Re}(qt))| \leq |\exp(-\text{Re}(pt))|$ .

Thus  $q$  must also be in the ROC.

Example:

$X(s) = \frac{(s-4)^2}{(s+1)(s+3)}$  has two poles at -1 and -3 as well as a double zero at 4. Its ROC is  $\{s: s > -1\}$ .

Final note:

Fourier Transform: if the imaginary axis ( $s = j\omega$ ) is entirely inside the ROC of  $X(s)$ , then the Fourier Transform  $X(f)$  exists. If  $s = j\omega$  is entirely outside,  $X(f)$  does not exist. If  $s = j\omega$  is the boundary of the ROC, the Fourier transform must be evaluated by other means due to the presence of poles (e.g. Try  $x(t) = u(t)$  )

## Note: Using matlab to find Laplace Transform

```

>> x1 = sym('cos(omega*t)')
x1 =
cos(omega*t)

>> X1 = laplace(x1)                                % Laplace Transform
X1 =
s/(s^2+omega^2)

>> pretty(X1)
          s
-----
      2      2
s +omega

>> X2 = sym('omega/(s^2+omega^2)')
X2 =
omega/(s^2+omega^2)

>> x2 = ilaplace(X2)                               % Inverse Laplace
x2 =
sin(omega*t)

>> dirac(0)                                         % Delta Function
ans =
inf
>> dirac(0.45)
ans =
0
>> laplace(sym('dirac(t)'))
ans =
1

>> heaviside(0)                                     % Step Function
ans =
NaN
>> heaviside(-13)
ans =
0
>> heaviside(1)
ans =
1
>> laplace(sym('heaviside(t)'))
ans =
1/s

```